

MATH 201: Linear Algebra

Week 3



Today:

* Start Chapter 2!

~ Matrix Multiplication ~

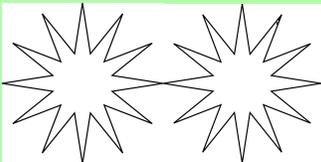
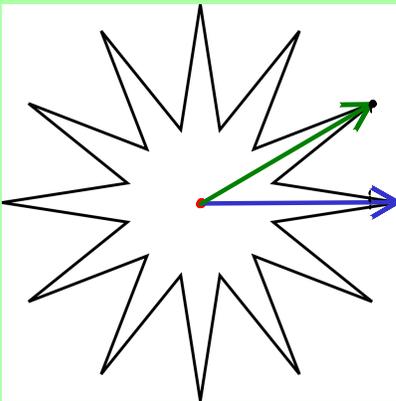
~ Linear Transformations ~

~ Matrix Inverses ~

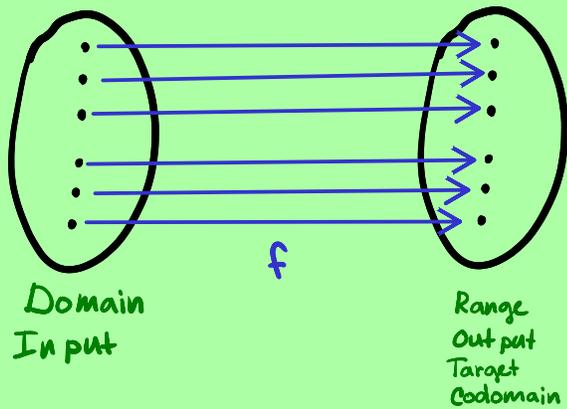


* Find a matrix that inputs the blue arrow and outputs the green arrow.

* How can matrices be used to represent translations?



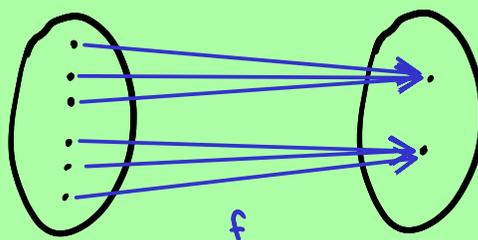
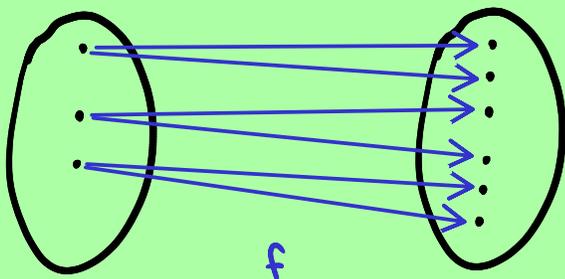
Review: Functions



$$* f(x) = x^2$$

$$* g(t) = \frac{t^2 - 6}{t - 1}$$

$$* f(x) = \sqrt{x^2}$$



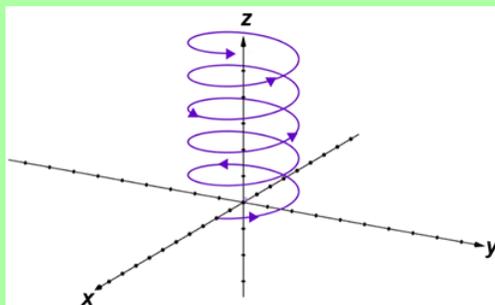
Parametric Functions and Vector Equations

$$\vec{r}: \mathbb{R} \rightarrow \mathbb{R}^3$$

$$t \mapsto \begin{bmatrix} \cos(t) \\ \sin(t) \\ t \end{bmatrix}$$

$$\text{proj}: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \mapsto \begin{bmatrix} x \\ y \end{bmatrix}$$



Composition

$$(\text{proj} \circ \vec{r}): \mathbb{R} \rightarrow \mathbb{R}^2$$

Matrix of projection: **No inverse.**

Definition: A function T from \mathbb{R}^m to \mathbb{R}^n is called a *linear transformation* if there exists an n by m matrix A such that

$$T(\vec{x}) = A\vec{x}$$

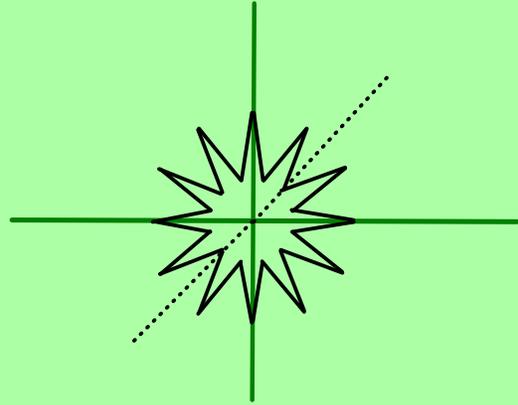
for all \vec{x} in \mathbb{R}^m .

Example:

$$y_1 = 7x_1 + 3x_2 - 9x_3 + 8x_4$$

$$y_2 = 6x_1 + 2x_2 - 8x_3 + 7x_4$$

$$y_3 = 8x_1 + 4x_2 \quad + 7x_4$$



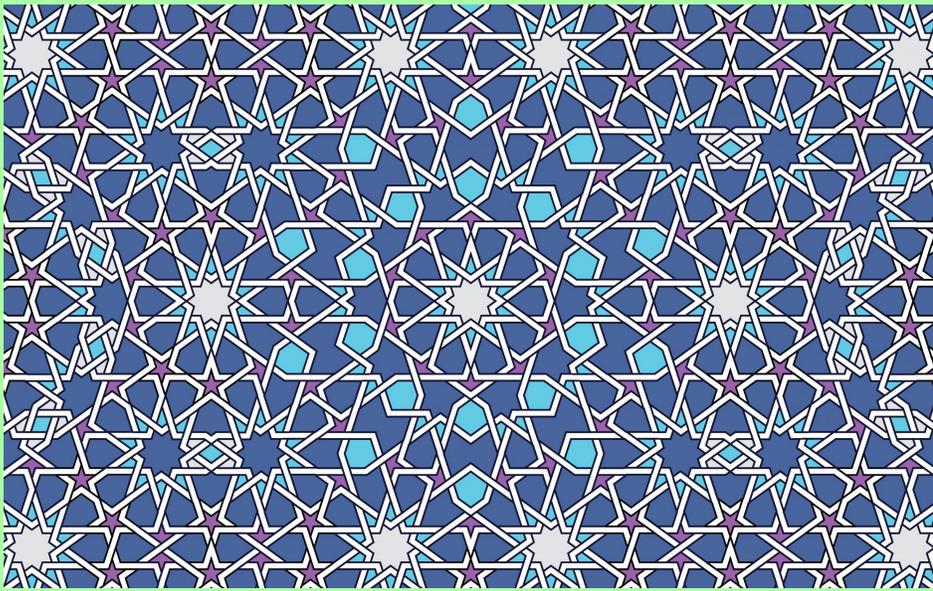
Definition: A function S from \mathbb{R}^m to \mathbb{R}^n is called an *affine transformation* if $T(x-y) = S(x) - S(y)$ is linear according to the above definition.

Example:

$$y_1 = 7x_1 + 3x_2 - 9x_3 + 8x_4 + 1$$

$$y_2 = 6x_1 + 2x_2 - 8x_3 + 7x_4 + 2$$

$$y_3 = 8x_1 + 4x_2 \quad + 7x_4 + 3$$



* What are the linear and affine symmetries?

* Suppose you can only make n types of tiles. How many different patterns can you make?

* Write a computer program that generates these...

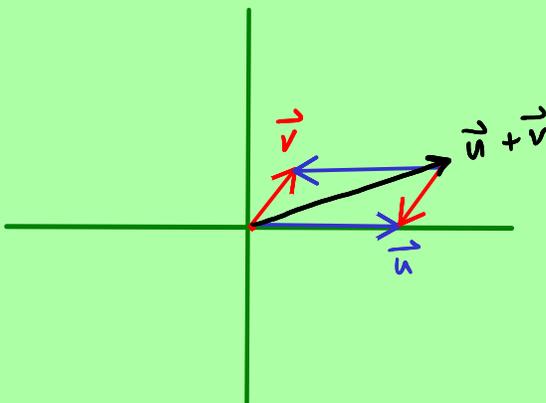
Further Reading: "Wallpaper Groups"

Theorem: Consider a linear transformation $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$. Then the matrix of T is

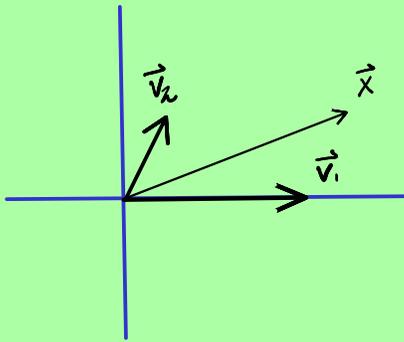
$$A = \begin{bmatrix} | & | & & | \\ T(\vec{e}_1) & T(\vec{e}_2) & \dots & T(\vec{e}_m) \\ | & | & & | \end{bmatrix} \quad \text{where } \vec{e}_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i^{\text{th}} \text{ component.}$$

Given $T(\vec{u}), T(\vec{v})$

* What can be said about $T(\vec{u} + \vec{v}), T(k\vec{v})$?



Example



Suppose...

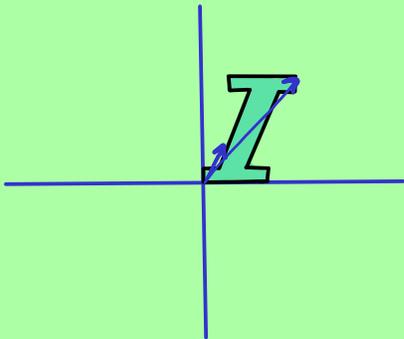
1. $T(\vec{v}_1) = \frac{1}{2} \vec{v}_1$

2. $T(\vec{v}_2) = 2 \vec{v}_2$

3. $\vec{x} = \vec{v}_1 + \vec{v}_2$

Sketch $T(\vec{x})$.

Example: Un-slant the letter using a matrix...



Hint 1:

Hint 2:

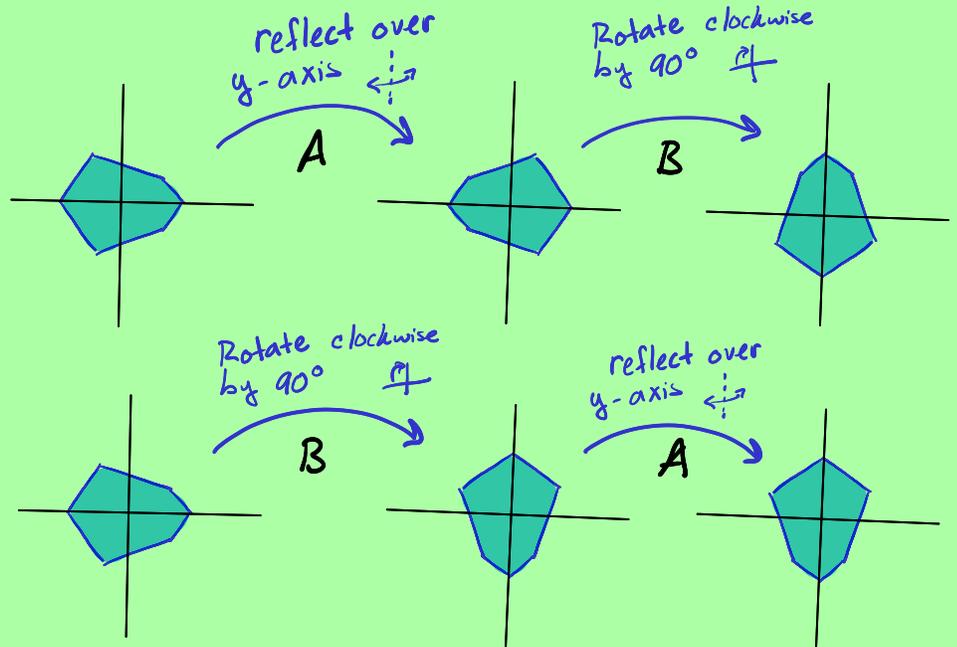
* Why will the same matrix work for all other letters?

Matrix Products

Definition:

- Let B be an $n \times p$ matrix and A a $q \times m$ matrix. The product BA is defined if and only if $p = q$.
 - If B is an $n \times p$ matrix and A is a $p \times m$ matrix then BA is the matrix of the linear transformation $T(\vec{x}) = (B \circ A)(\vec{x}) = B(A(\vec{x}))$.
- * Why is this the same as the "row times column" rule?

Theorem: Matrix multiplication is non-commutative!



* Which matrices commute with all others?

* For various shapes, which symmetries commute?

Other Properties...

* Identity

$$A \cdot I = I \cdot A = A$$

* Associativity

$$(AB)C = A(BC)$$

* Distributive Property

$$A(C + D) = AC + AD$$

* Commutativity of scalar multiplication

$$(kA)B = A(kB)$$